## CaTT: A type theoretic approach to weak $\omega$ -categories

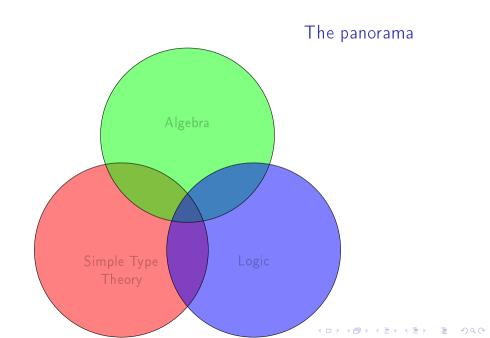
#### Thibaut Benjamin, Eric Finster, Samuel Mimram

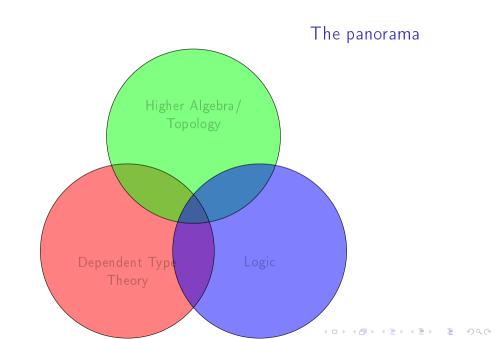
15 February 2021

Seminaire LACL

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# Introduction





Categories are made of

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objects

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Categories are made of



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Equipped with



Categories are made of



Equipped with

identities

$$x \rightsquigarrow x \xrightarrow{\operatorname{id}_x} x$$

Categories are made of

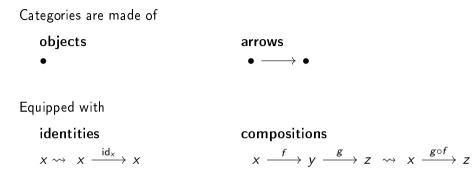


Equipped with

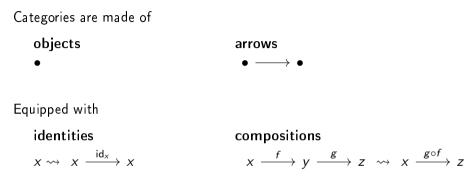
identities

 $x \rightsquigarrow x \xrightarrow{id_x} x$ 

compositions  $x \xrightarrow{f} y \xrightarrow{g} z \rightsquigarrow x \xrightarrow{g \circ f} z$ 

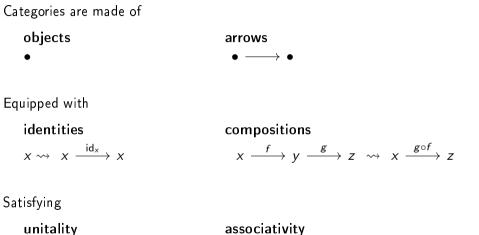


Satisfying



Satisfying

 $unitality f \circ id_x = f = id_y \circ f$ 



 $f \circ \operatorname{id}_x = f = \operatorname{id}_y \circ f$ 

associativity  $h \circ (g \circ f) = (h \circ g) \circ f$ 

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- ▷ Every monoid M is a category : objects =  $\{\bullet\}$ , morphisms = M
- A rewriting system is a category : objects = terms, morphisms = rewriting relations.

Categories are ubiquitous, they are notably useful for:

 $\triangleright$  Modeling functional programming (objects = types, morphisms =  $\lambda$ -terms)

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- Encoding propositions and implications
- Defining algebraic structures
- And many other things...

Provide a common framework to study programming languages, logic and algebra  ${\bf l}_{\rm r}$  Semantics

## Foreshadowing: Type theoretic formulation of categories Categories are made of objects arrows • $\bullet \longrightarrow \bullet$ Equipped with identities compositions $x \xrightarrow{f} y \xrightarrow{g} z \rightsquigarrow x \xrightarrow{g \circ f} z$ $x \rightsquigarrow x \xrightarrow{id_x} x$

Satisfying **unitality**  $f \circ id_x = f = id_y \circ f$ 

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 $f \circ \operatorname{id}_{X} = f = \operatorname{id}_{Y} \circ f$ 

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 $\frac{\mathsf{identities}}{\Gamma \vdash x : \star}$ 

 $\frac{\mathsf{compositions}}{\Gamma \vdash f : x \rightarrow y \qquad \Gamma \vdash g : y \rightarrow z}{\Gamma \vdash g \circ f : x \rightarrow z}$ 

Satisfying **unitality**  $f \circ id_x = f = id_y \circ f$ 

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Satisfying unitality  $\frac{\Gamma \vdash f : x \rightarrow y}{\Gamma \vdash f \circ id(x) \equiv f \equiv id(y) \circ f}$ 

associativity  $h \circ (g \circ f) = (h \circ g) \circ f$ 

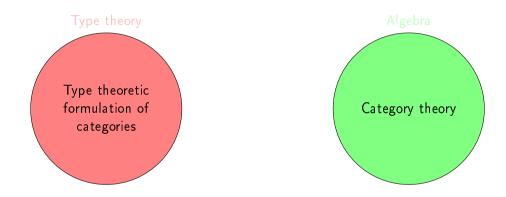
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#### Foreshadowing: Type theoretic formulation of categories Categories are made of objects arrows $\Gamma \vdash x : \star \qquad \Gamma \vdash y : \star$ $\Gamma \vdash$ $\Gamma \vdash x \rightarrow v$ $\Gamma \vdash \star$ Equipped with identities compositions $\Gamma \vdash f : x \rightarrow y \qquad \Gamma \vdash g : y \rightarrow z$ $\Gamma \vdash x : \star$ $\Gamma \vdash id(x) : x \rightarrow x$ $\Gamma \vdash g \circ f : x \rightarrow z$ Satisfying

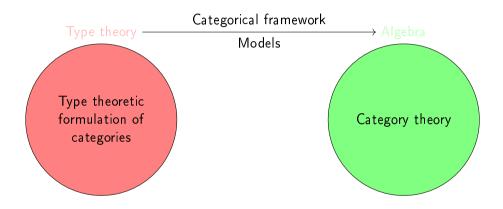
unitality  $\Gamma \vdash f \circ \mathsf{id}(x) \equiv f \equiv \mathsf{id}(v) \circ f$ 

associativity  $\Gamma \vdash f : x \rightarrow y$   $\Gamma \vdash f : x \rightarrow y$   $\Gamma \vdash g : y \rightarrow z$   $\Gamma \vdash h : z \rightarrow w$  $\Gamma \vdash h \circ (g \circ f) \equiv (h \circ g) \circ f$ ▲□▶ ▲□▶ ▲□▶ ▲□▶ □ の 0 0

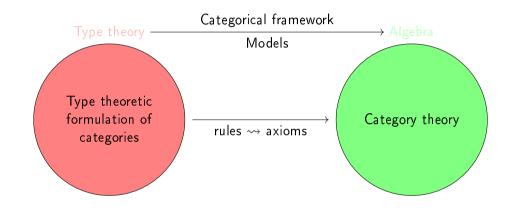
#### Semantics



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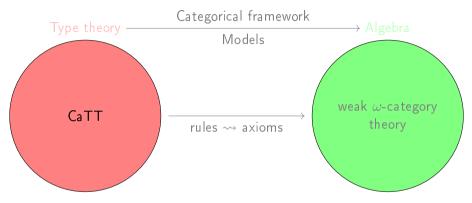
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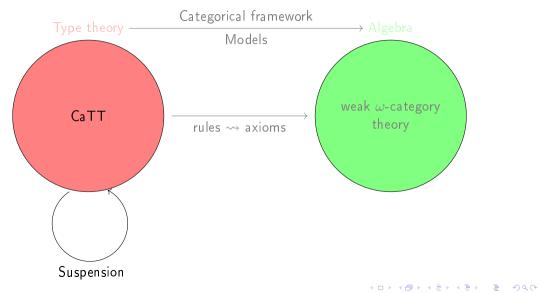
#### Theorem

The models of the type-theoretic formulation of categories are the categories.

### In this presentation



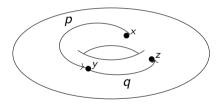
### In this presentation



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Some situation that ought to be categories

▷ paths in topological spaces

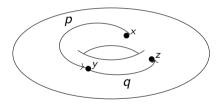


But: The composition is not associative

$$(p*q)*r \neq p*(q*r)$$

Some situation that ought to be categories

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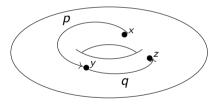
The composition is associative up to homotopy

$$(p*q)*r \Rightarrow p*(q*r)$$

Some situation that ought to be categories

▷ paths in topological spaces

Identity types in Martin-Löf type theory



trans: 
$$\prod A : U$$
,  $\prod x \ y \ z : A$ ,  
 $x = y \rightarrow y = z \rightarrow x = z$   
trans  $A \times x \times refl refl := refl$ 

The composition is associative up to homotopy

$$(p*q)*r \Rightarrow p*(q*r)$$

But: Transitivity is not associative

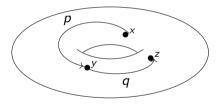
 $\texttt{trans}(\texttt{trans} \ p \ q) \ r \not\equiv \texttt{trans} \ p \ (\texttt{trans} \ q \ r)$ 

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Some situation that ought to be categories

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Identity types in Martin-Löf type theory



$$\begin{array}{l} \texttt{trans:} & \prod A: \mathcal{U}, \ \prod x \ y \ z: A, \\ & x = y \rightarrow y = z \rightarrow x = z \\ \texttt{trans} & A \times x \ \texttt{refl refl := refl} \end{array}$$

The composition is associative up to homotopy

$$(p*q)*r \Rightarrow p*(q*r)$$

There is a proof term for associativity assoc:  $\prod A : U$ ,  $\prod x y z w : A$ ,  $\prod p : x = y$ ,  $\prod q : y = z$ ,  $\prod r : z = w$ , trans(trans p q) r = trans p (trans q r)

## Higher categories

#### We can encode this defect into cells of higher dimension

### Weak $\omega$ -categories

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#### Weak $\omega$ -categories = globular sets + compositions

A globular set is composed of

▷ points (or objects) : ●

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- $\triangleright$  arrows (or 1-cells) :  $\longrightarrow$  •

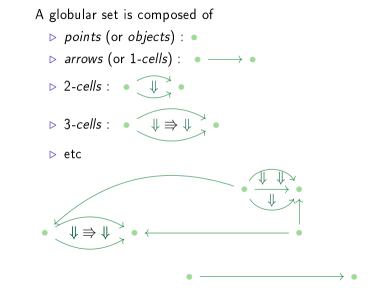


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- ▷ 2-cells :  $\bigcirc$  •

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- $\triangleright$  2-cells :  $\checkmark$  •
- $\triangleright \ 3\text{-cells}: \quad \bullet \quad \Downarrow \Rightarrow \Downarrow \stackrel{\checkmark}{\rightarrow} \bullet$

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- ⊳ etc



We require that these cells compose

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▷ Arrows:





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 $\stackrel{\times}{\bullet} \xrightarrow{f} \stackrel{y}{\bullet} \xrightarrow{g} \stackrel{z}{\bullet} \xrightarrow{z} \xrightarrow{z} \xrightarrow{z} \stackrel{z}{\bullet} \xrightarrow{z} \stackrel{z}{\bullet} \xrightarrow{z} \xrightarrow{g \circ f} \stackrel{z}{\bullet} \xrightarrow{z} \xrightarrow{g \circ f} \xrightarrow{g \circ$ 

▷ 2-cells:

Vertical composition f  $\downarrow \alpha$   $\downarrow \beta$   $\downarrow \beta$  $\downarrow \beta$ 

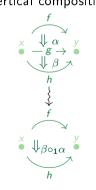
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#### We require that these cells compose

▷ Arrows:

$$\overset{\times}{\bullet} \xrightarrow{f} \overset{y}{\bullet} \xrightarrow{g} \overset{g}{\longrightarrow} \overset{z}{\bullet} \xrightarrow{} \overset{\times}{\longrightarrow} \overset{\chi}{\bullet} \xrightarrow{g \circ f} \overset{z}{\bullet}$$

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Vertical composition

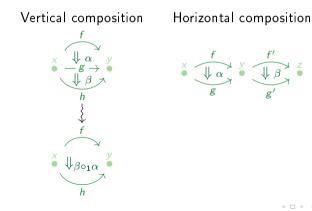
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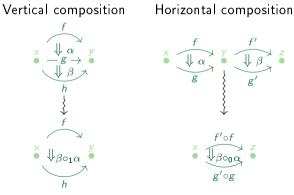


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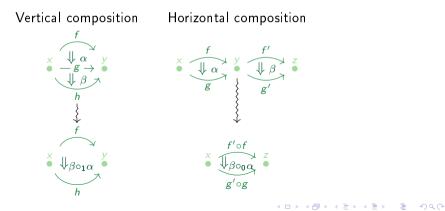


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▷ 2-cells:



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 $\bullet \longrightarrow \bullet \longrightarrow \bullet \longrightarrow \bullet$ 

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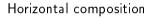


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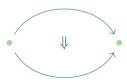
Vertical composition



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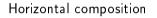


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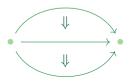
Vertical composition



 $\bullet \longrightarrow \bullet \longrightarrow \bullet \longrightarrow \bullet$ 





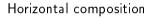


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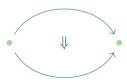
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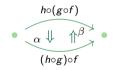


# Everything is weak!

All the above-mentioned equalities are weak: they are equivalences

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# Pasting schemes

The pasting schemes are the globular set that have one unambiguous way of being fully composed

They are well-ordered and do not have any hole



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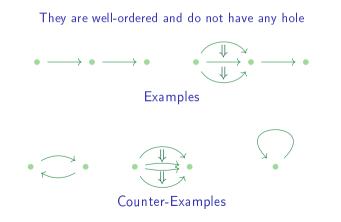
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# Pasting schemes

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# The Grothendieck-Maltsiniotis definition

Existence of compositions:
 Every pasting scheme can be composed

# The Grothendieck-Maltsiniotis definition

- Existence of compositions:
   Every pasting scheme can be composed
- Generalized "Associativities":

Any two ways of composing a same pasting scheme are related by a higher cell

The type theory CaTT

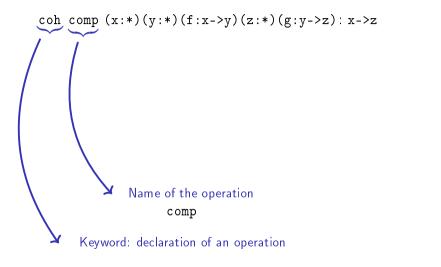


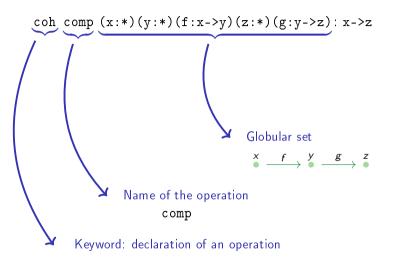
coh comp (x:\*)(y:\*)(f:x->y)(z:\*)(g:y->z): x->z

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coh comp (x:*)(y:*)(f:x->y)(z:*)(g:y->z): x->z
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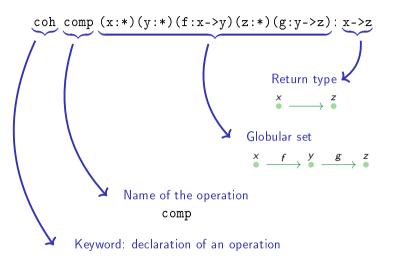
Keyword: declaration of an operation

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coh comp (x:\*)(y:\*)(f:x->y)(z:\*)(g:y->z): x->z

$$\overset{X}{\bullet} \xrightarrow{f} \overset{Y}{\bullet} \xrightarrow{g} \overset{Z}{\longrightarrow} \overset{Z}{\bullet} \qquad \stackrel{X}{\bullet} \xrightarrow{comp \ f \ g} \overset{Z}{\longrightarrow} \overset{Z}{\longrightarrow}$$

Composition of two arrows

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coh comp (x:\*)(y:\*)(f:x->y)(z:\*)(g:y->z): x->z

$$\overset{X}{\bullet} \xrightarrow{f} \overset{Y}{\bullet} \xrightarrow{g} \overset{Z}{\bullet} \xrightarrow{\chi} \overset{X}{\bullet} \xrightarrow{\text{comp f g}} \overset{Z}{\bullet}$$

Composition of two arrows

coh id (x:\*) : x -> x

coh comp (x:\*)(y:\*)(f:x->y)(z:\*)(g:y->z): x->z

$$\overset{X}{\bullet} \xrightarrow{f} \overset{Y}{\bullet} \overset{g}{\longrightarrow} \overset{Z}{\bullet} \qquad \stackrel{X}{\longrightarrow} \qquad \overset{comp f g}{\longrightarrow} \overset{Z}{\bullet}$$

Composition of two arrows

coh id (x:\*) : x->x



Identity of an object

In order to manipulate  $\omega$ -categories, we need:

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 $\triangleright$  a type  $\star$  for objects:

# $\frac{\Gamma \vdash}{\Gamma \vdash \star}$

#### In order to manipulate $\omega$ -categories, we need:

▷ a type ★ for objects:

 $\triangleright$  a type  $\rightarrow$  for arrows:

 $\frac{\Gamma \vdash}{\Gamma \vdash \star}$   $\frac{\Gamma \vdash t : \star \quad \Gamma \vdash u : \star}{\Gamma \vdash t \to u}$ 

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$$\begin{array}{c} & \Gamma \vdash \\ \hline \Gamma \vdash \star \end{array} \\ \triangleright \text{ a type} \rightarrow \text{ for arrows:} \\ & \Gamma \vdash t : \star \quad \Gamma \vdash u : \star \\ \hline \Gamma \vdash t \to u \end{array} \\ \hline & \Gamma \vdash f : t \to u \\ \hline & \Gamma \vdash g : t \to u \\ \hline & \Gamma \vdash f \Rightarrow g \end{array}$$

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⊳ etc

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In order to manipulate  $\omega$ -categories, we need:

 $\triangleright$  a type  $\star$  for objects:

$$\triangleright \text{ a type} \rightarrow \text{ for all } \geq 1\text{-cells} \qquad \qquad \frac{\Gamma \vdash}{\Gamma \vdash \star} \\ \frac{\Gamma \vdash t : A \qquad \Gamma \vdash u : A}{\Gamma \vdash t \rightarrow u}$$

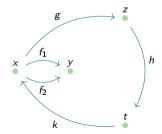
# Contexts are diagrams!

$$\left\{ \begin{array}{cccc} x:\star, & y:\star, & z:\star, & t:\star \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & & \\ & & & \\ & & & & \\ & & & \\ & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & & \\ & &$$

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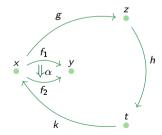
# Contexts are diagrams!

$$\Gamma \left\{ \begin{array}{cccc}
x : \star, & y : \star, & z : \star, & t : \star \\
f_1 : x \xrightarrow{} y, & f_2 : x \xrightarrow{} y, & g : x \xrightarrow{} z, & h : z \xrightarrow{} t, & k : t \xrightarrow{} x \\
\end{array} \right.$$



# Contexts are diagrams!

$$\Gamma \begin{cases}
x : \star, & y : \star, & z : \star, & t : \star \\
f_1 : x \xrightarrow{} y, & f_2 : x \xrightarrow{} y, & g : x \xrightarrow{} z, & h : z \xrightarrow{} t, & k : t \xrightarrow{} x \\
\alpha : f_1 \xrightarrow{} y & f_2 \\
x \xrightarrow{} y & x & x & x
\end{cases}$$



### **PS**-contexts

> The ps-contexts are the contexts corresponding to pasting schemes.

They are recognized by a judgment  $\Gamma \vdash_{ps}$ 

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> This judgment is decidable with an algorithm

 $\frac{\Gamma \vdash_{ps} x : A}{\prod_{j \in ps} f : x \xrightarrow{j} y}$   $\frac{\Gamma \vdash_{ps} f : x \xrightarrow{j} y}{\Gamma \vdash_{ps} y : A}$   $\frac{\Gamma \vdash_{ps} x : x}{\Gamma \vdash_{ps} x}$ 

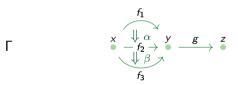
Every ps-context  $\Gamma$  has a source  $\partial^{-}(\Gamma)$  and a target  $\partial^{+}(\Gamma)$  (which are ps-contexts themselves)

Intuitively, composing fully the ps-context yields a cell from its source to its target

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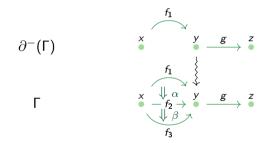


Example

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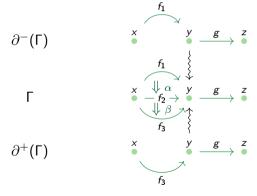
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Example

### Interpretation

▷ A term  $\Gamma \vdash t$ : A corresponds to a composition of certain cells of  $\Gamma$ . More precisely: a cell in the weak  $\omega$ -catégory freely generated by the globular set corresponding to  $\Gamma$ .

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▷ A term Γ ⊢ t : A corresponds to a composition of certain cells of Γ. More precisely: a cell in the weak ω-catégory freely generated by the globular set corresponding to Γ.

▷ Case of ps-contexts  $\Gamma \vdash_{ps}$ :

 $\begin{array}{c} \Gamma \vdash t : A \\ \mathsf{Var}(t : A) = \mathsf{Var}(\Gamma) \end{array} \right\} \qquad t \text{ is a way of composing completely the ps-context } \Gamma. \end{array}$ 

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### Operations and coherences

▷ Existence of compositions:

Every pasting scheme can be composed

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Every pasting scheme can be composed

Rule for generating these compositions:

$$\frac{\Gamma \vdash_{\mathsf{ps}} \quad \partial^{-}(\Gamma) \vdash t : A \quad \partial^{+}(\Gamma) \vdash u : A}{\Gamma \vdash \mathsf{op}_{\Gamma, t \xrightarrow{A} u} : t \xrightarrow{A} u}$$

 $Var(t : A) = Var(\partial^{-}(\Gamma))$  $Var(u : A) = Var(\partial^{+}(\Gamma))$ 

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$$\Gamma = x : \star, y : \star, f : x \underset{\star}{\rightarrow} y, z : \star, g : y \underset{\star}{\rightarrow} z$$
$$\Gamma \vdash \operatorname{comp} : x \rightarrow z$$

Example

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 $Var(t : A) = Var(\Gamma)$  $Var(u : A) = Var(\Gamma)$ 

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$$\begin{split} & \Gamma = x: \star, y: \star, f: x \underset{\star}{\rightarrow} y, z: \star, g: y \underset{\star}{\rightarrow} z, w: \star, h: z \underset{\star}{\rightarrow} w \\ & \Gamma \vdash \texttt{assoc:comp f}(\texttt{comp g h}) {\rightarrow} \texttt{comp f}(\texttt{comp f g}) \texttt{h} \end{split}$$

Example

# $Suspension \ in \ CaTT$

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## A problem with CaTT

Writing in CaTT may be very tedious :

 $x \rightsquigarrow x \xrightarrow{\mathsf{id}_x} x$ 

coh id (x:\*):x ->x

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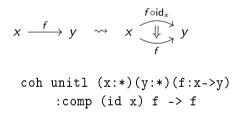
$$x \xrightarrow{f} y \xrightarrow{g} z \xrightarrow{g \circ f} z$$
  
coh comp (x:\*)(y:\*)(f:x->y)  
(z:\*)(g:y->z):x->z

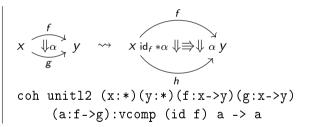
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$$\begin{array}{c|c} \xrightarrow{g \circ f} z \\ x \xrightarrow{-g \to y} & \xrightarrow{f} y \\ h \\ x \to y) \\ x \to y) \\ (a:f - g) (h:x \to y) (b:g \to h):f \to h \end{array}$$

## A problem with CaTT

Writing in CaTT may be very tedious :





### A solution: the suspension

Idea: Write only the left term and let the software generate the right one.

coh id (x:\*):x->x  $\xrightarrow{\text{suspension}}$  coh id2 (x:\*)(y:\*)(f:x->y):f->f

Practice: Generate the terms on the fly using the dimension of the argument.

coh id	(x:*):x->x	
let ex	(x:*)(y:*)(f:x->y)=id f	~~

coh id (x:\*):x->x
coh id2 (x:\*)(y:\*)(f:x->y):f->f
let ex (x:\*)(y:\*)(f:x->y)=id2 f

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$$\Sigma \varnothing = (x_0 : \star, y_0 : \star)$$
  $\Sigma(\Gamma, x : A) = \Sigma \Gamma, x : \Sigma A$ 

$$\Sigma \varnothing = (x_0 : \star, y_0 : \star) \qquad \Sigma(\Gamma, x : A) = \Sigma \Gamma, x : \Sigma A$$
  
$$\Sigma \star = x_0 \underset{\star}{\rightarrow} y_0 \qquad \Sigma(t \underset{\Delta}{\rightarrow} u) = \Sigma t \underset{\Sigma A}{\longrightarrow} \Sigma u$$

$$\begin{split} \Sigma \varnothing &= (x_0 : \star, y_0 : \star) \\ \Sigma \star &= x_0 \mathop{\longrightarrow}\limits_{\star} y_0 \\ \Sigma x &= x \end{split} \qquad \begin{aligned} \Sigma (\Gamma, x : A) &= \Sigma \Gamma, x : \Sigma A \\ \Sigma (t \mathop{\longrightarrow}\limits_{A} u) &= \Sigma t \mathop{\longrightarrow}\limits_{\Sigma A} \Sigma u \\ \Sigma (\operatorname{coh}_{\Gamma, A} [\gamma]) &= \operatorname{coh}_{\Sigma \Gamma, \Sigma A} [\Sigma \gamma] \end{split}$$

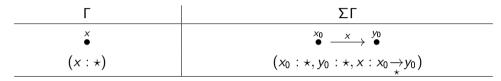
Induction over the syntax: Define the suspension as a meta-operation on the syntax of the type theory.

$$\begin{split} \Sigma \varnothing &= (x_0 : \star, y_0 : \star) \\ \Sigma &= x_0 \mathop{\longrightarrow}\limits_{\star} y_0 \\ \Sigma &= x \\ \Sigma &= x \\ \Sigma &= x \\ \Sigma &= \chi \\$$

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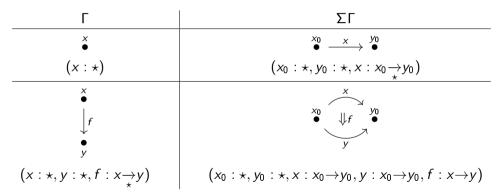
## Illustration

#### On contexts:



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## Well-definedness of the suspension

$$\begin{split} \Sigma \varnothing &= (x_0 : *, y_0 : *) \\ \Sigma &= x_0 \to y_0 \\ \Sigma &= x \\ \Sigma &= x \\ \Sigma &= \langle x_0 \mapsto x_0, y_0 \mapsto y_0 \rangle \end{split} \qquad \begin{split} \Sigma &(\Gamma, x : A) = \Sigma \Gamma, x : \Sigma A \\ \Sigma &(\Gamma \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma u \\ \Sigma &(\tau \to u) = \Sigma T \to \Sigma T \\ \Sigma &(\tau \to u) =$$

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Theorem (B., Mimram) The following rules are derivable

$$\frac{\Gamma \vdash}{\Sigma \Gamma \vdash} \qquad \frac{\Gamma \vdash A}{\Sigma \Gamma \vdash \Sigma A} \qquad \frac{\Gamma \vdash t : A}{\Sigma \Gamma \vdash \Sigma t : \Sigma A} \qquad \frac{\Delta \vdash \gamma : \Gamma}{\Sigma \Delta \vdash \Sigma \gamma : \Sigma \Gamma}$$

## Well-definedness of the suspension

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$$\begin{split} \Sigma \varnothing &= (x_0 : *, y_0 : *) \\ \Sigma &= x_0 \rightarrow y_0 \\ \Sigma &= x \\ \Sigma(\langle \rangle) &= \langle x_0 \mapsto x_0, y_0 \mapsto y_0 \rangle \end{split} \qquad \begin{split} \Sigma &(\Gamma, x : A) = \Sigma \Gamma, x : \Sigma A \\ \Sigma &(\Gamma, x) = \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} A u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma A \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma T \xrightarrow{} \Sigma X \\ \Sigma(t \xrightarrow{} X u) &= \Sigma \Sigma X \\ \Sigma(t \xrightarrow{$$

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#### Proof.

By induction over the rules of the theory

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Internally:

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▷ The system computes the difference in the dimension of the argument unit expects an argument of dimension 1, a is of dimension 2 →→ suspend once

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#### Internally:

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- ▷ Compute the suspension of unit

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Problem: This operation is not always well-defined. It only defines a partial endomorphism of CwFs

# Thank you!

